Medical Cyber-Physical Systems: IoMT Applications and Challenges

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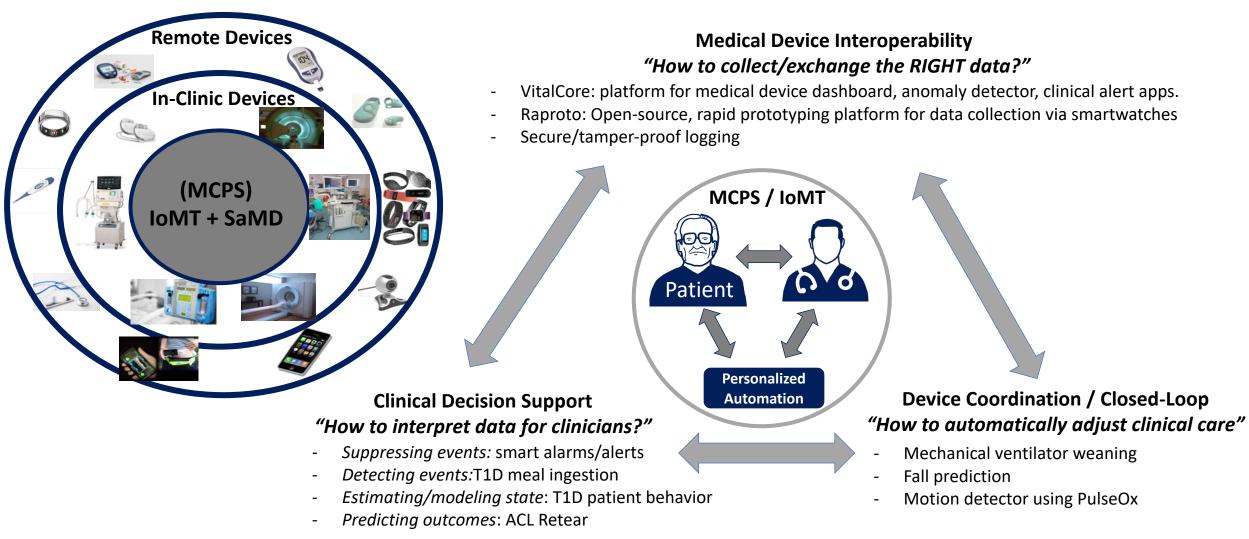
University of Pennsylvania

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PRECISE



IoMT Research

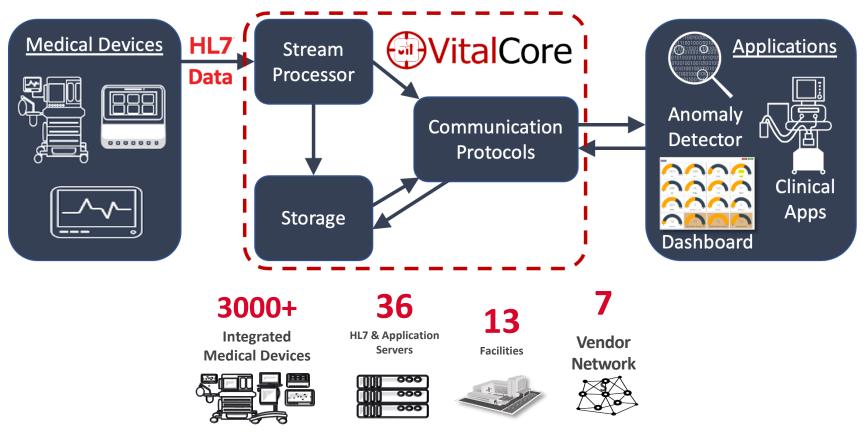


Challenges

- 1. IoMT/MCPS should be implemented in such a manner to reduce clinician load, not add to it.
- 2. Because of the reliance on high-quality data the first and often the most time-consuming step in many research endeavors is to build a data collection system.
- 3. Medical applications require high quality data from reliable, humansafe devices. Further, they present data storage issues and need ample processing and analysis to create useful applications.

Infrastructure: @VitalCore

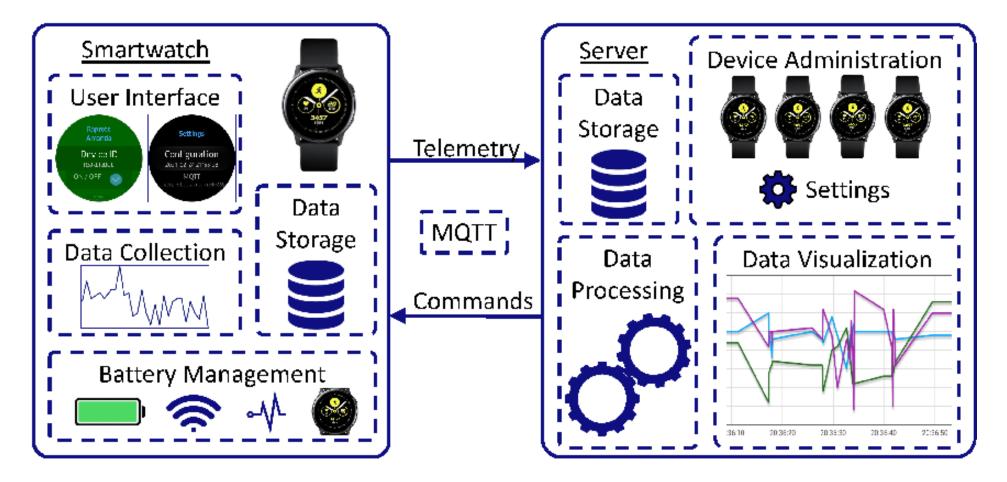
Analytics & Support Dashboard for Medical Device Integration



And growing...



Open-source, rapid prototyping platform for data collection via smartwatches



Applications: SmartAlarms

- Medical device alarms are non-informative
 - between 80% and 99% of all alarms are false
- Clinicians have developed alarm fatigue and may not respond to alarms
 - A top 10 health technology hazard since 2007
- Solution: Smart alarm suppression
 - Maximally suppress alarms non-informative alarms without suppressing actionable alarms
- Initially consider low SpO2 alarms
 - "Reducing Pulse Oximetry False Alarms Without Missing Life-Critical Events" (CHASE 2018)
 - ECRI 2019 #7 Health Tech Hazard: Improper Customization of Physiologic Monitor Alarm Settings May Result in Missed Alarms





Human-in-the-loop MCPS/IoMT

- Clinicians and/or patients operate and coordinate medical devices
- Analysis of safety and effectiveness needs to take operator behavior into consideration
 - How much the operator trusts the system
 - When and how operator interferes with automation
- Case study: patient-operated insulin pump
 - Smart pump suggest doses
 - Patients input carb intake
 - Patients can accept or adjust dose
 - How does behavior affect treatment?







Penn RT-ACL: Identification of High-Risk Youth Patients and their Most Significant Risk Factors to Reduce Engineering Anterior Cruciate Ligament Reinjury Risk National Institute PRECISE of Health Amanda Watson¹, Pengyuan Lu¹, Elliot Greenberg¹, J. Todd R. Lawrence², Theodore J. Ganlev², Insup Lee¹, James Weimer¹ Renn Medicine University of Pennsylvania¹, Children's Hospital of Philadelphia Motivation Conclusion 30% Retear their ACL The RT-ACL system identifies high-risk patients and determines their most significant risk factors to >6 Months Recovery ACL Tears Annually in reduce ACL reinjury risk: High risk patients are 4.6x as likely to retear as low risk patients the US Evaluation on 441 youth patients, 8-21 years of age that underwent an ACL reconstruction at the Children's Hospital of Philadelphia 1 in 60 Next Steps: Youth Multi-year Clinical Validation at Children's Hospital of Philadelphia Athletes Generalized System Development \$2 Billion Annually in Medical Costs · Integration into the EHR **Research Overview Data Collection Clinical Decision Support** Aim: Identify patients at high risk for ACL Retear Dataset: Analyzed Clinical Notes Aim: Develop a decision support system that is easy-to-use and is trusted by clinicians to aid in decision making for ventilation weaning **RT-ACL Model** Feedback System Patient Dat Risk Level Example Category # Missing Risk Level Indicator Based on votes from the expert Fraining Datase Demographics 5% Age, DOB 6 Medium created features and labeling Injury Inforation 2% Date, Sport Played 2 Impact Relative with ACL Tear? Family History 43% 2 functions. A risk stratification is Surgery Information 20 9% Type of Reconstruction lost Significant Risk Factors **Risk Factor** applied that features an increasing 14% Single Leg Hop Distance Time to Release for Activity Date of Release to Activity Recovery Information 2 Identification Re-tear Information retear rate as patients move through Risk Factors 213 Rehab Information Ease of Modifica

Risk Factor Evaluation

Our approach: Leverage expert knowledge to intelligently design

machine learning algorithms. Classify patient risk of retear as high

Risk

Low

Risk

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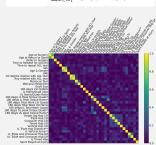
features that a predictive of risk. Combine these features using

medium or Low.

Feature 2

Penn





	Date of Release to Activity				
59% Time to Repeat ACL Tear					
79% Triple Hop LSI					
1970 Inple hop LSI					
				_	
	High Risk		Low Risk		Unlabeled
Risk Factor	W	#	W	#	#
Age at Return to Sport	37	188	11	27	139
Delay to Surgery	32	31	14	14	323
Time to Release for Activity	33	227	23	51	76
Time to repeat ACL tear	92	36	69	22	296
Age and Sex	29	193	37	161	0
BMI	32	284	25	8	62
1st Degree Relative ACL Tear	23	40	31	87	227
Any relative ACL tear	26	31	30	96	227
Meniscus tear	28	226	37	71	57
Meniscus resection	23	92	33	205	57
Graft Size	18	11	38	126	57
180 deg/s LSI Quads	31	101	41	130	123
IL Hams/Quads Ratio	32	307	34	44	3
UL Hams/Quads Ratio	32	304	36	47	3
180 deg/s IL PT Quads*	28	110	35	241	3
180 deg/s IL PT Hams*	26	109	36	242	3
180 deg/s Ttl Work LSI Quads	28	139	36	129	86
180 deg/s Ttl Work LSI Hams	34	173	29	80	101
180 deg/s IL Ttl Work Quads	36	110	31	240	4
180 deg/s UL PT Quads*	26	221	43	131	2
180 deg/s UL PT Hams*	33	109	32	242	3
Single Leg Hop LSI	19	32	43	129	193
Triple Hop LSI	31	29	36	140	185
Crossover Hop LSI	54	13	53	69	272
Timed Hop LSI	18	11	53	86	257
Vertical Hop LSI	34	62	40	111	181
IL Triple Hop Distance(cm)**	43	101	39	106	147
IL Vertical Jump(cm)**	44	18	47	82	254
IL Triple & Crossover Hop Dif	52	42	54	82	230
UL Triple & Crossover Hop Dif	54	46	53	78	230

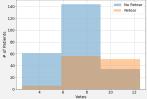
49 37 102 253 55 45 34 207 67

11

IL Timed Hop

Sport Played at Injury

the bins.



Binning

Group patents by how likely they are to retear



High risk patients are 4.6x as likely to retear as low risk patients

Feedback System

Timed Hop LSI final

Name: 173, dtype: float64

Patient #: 607.0 Risk Level: High Votes: 10.532917410200376 Votes to lower risk level: 1.2061838279777248 Highest Risk Features: Involved Limb Timed Hop final 0.555556 0.543478 Difference between triple and corssover hop Uninvolved final Difference between triple and crossover hop Involved final 0.543210 Crossover Hop LSI_final 0.538462 0.529412

Levels of Autonomy

444 No Driver Partial Conditional High Automation Full Automation Assistance Automation Automation Automation Zero autonomy; the /ehicle is controlled b Vehicle has combined The vehicle is capable river is a necessity, bu he vehicle is capable driver performs al the driver, but some automated functions s not required to monito performing all driving performing all driving driving tasks. driving assist features like acceleration and the environment. The inctions under certai functions under all may be included in the steering, but the drive lriver must be ready to conditions. The driver conditions. The drive ehicle design. must remain engaged take control of the may have the option t may have the option to ith the driving task and vehicle at all times control the vehicle control the vehicle with notice nitor the environme at all times

SOCIETY OF AUTOMOTIVE ENGINEERS (SAE) AUTOMATION LEVELS

Increasingly human-performed tasks

Increasingly machine-performed tasks

Caregiver(s) performs the task

No autonomy

Caregiver(s) is involved in task and technology aids and enhances effectiveness

Caregiver(s) initiates a task and has discrete control over technology that executes it

Caregiver(s) defines and initiates a task & technology executes the task with caregiver supervision

> Conditional Autonomy

Technology decides course of action and executes it with caregiver supervision

Technology decides course of action and executes it without supervision

Full Auto

Technology Assistance

Task Autonomy

High Autonomy Full Autonomy

Conclusion

- We are pushing towards a vision of the future in which technology autonomously provides comprehensive medical care.
- As we strive towards this reality, we have developed the IoMT and MCPS, but we still have many more challenges to surpass.